

Operation

Research

Quadratic Programming

Problems

(After the Kuhn-Tucker Conditions).

Wolfe's Modified Simplex Method \rightarrow The Wolfe's method for solving a quadratic programming problem can be summarized as:-

Step 1 \rightarrow Introduce artificial variable A_j in Kuhn-Tucker conditions

$$C_j - \sum_{k=1}^n x_k d_{jk} - d_i a_{ij} + u_i + A_j = 0$$

for a starting feasible solution we shall have

$$x_j = 0; u_i = 0, a_j = -C_j \text{ \& } s_i^2 = b_i$$

Step 2:- Apply phase Ist of simplex method to check the feasibility of constraint eqⁿ $AX \leq b$. If there is no feasible solⁿ terminate the solⁿ procedure otherwise get an initial basic feasible solution for phase 2. To obtain the desired feasible solⁿ for the following problem.

$$\text{Min } Z = \sum_{j=1}^n A_j$$

$$\sum_{k=1}^n x_k d_{jk} - d_i a_{ij} + u_i + A_j = -C_j$$

$$\sum_{j=1}^n a_{ij} x_j + s_i^2 = b_i$$

$$\left. \begin{array}{l} d_i s_i = 0 \\ u_i x_i = 0 \end{array} \right\} \begin{array}{l} \text{these are known as} \\ \text{Complementary slackness conditions.} \end{array}$$

Thus while deciding for a variable to enter into the bases at each iteration the complementary slackness conditions must be satisfied.

Step 3 \rightarrow Apply two phase of simplex method to get optimum solution.

Question: 1 Wolfe's modified simplex method:

$$\text{Max } Z = 4x_1 + 6x_2 - 2x_1^2 - 2x_1x_2 - 2x_2^2$$

$$\text{Subject to, } x_1 + x_2 \leq 2$$

$$\& x_1, x_2 \geq 0$$

Solⁿ:

Step 1: (a) Firstly, to convert the objective function into maximize form

(b) Write all constraint inequalities with \leq sign

{ Since we have two decision variables, so we have two new constraints.

$$x_1 + 2x_2 \leq 2$$

$$x_1 \geq 0$$

$$x_2 \geq 0$$

(c) Convert the inequalities into the equations by adding slack variables

$$x_1 + 2x_2 + S_1^2 = 2$$

$$-x_1 + S_2^2 = 0$$

$$-x_2 + S_3^2 = 0$$

{ Since it is Quadratic programming so the slack variables are also in square form.

(d) To obtain the Kuhn-Tucker condition, we form the Lagrange's funcⁿ

$$L(x_1, x_2, S_1, S_2, S_3, d, u_1, u_2) = 4x_1 + 6x_2 - 2x_1^2 - 2x_1x_2 - 2x_2^2 - d(x_1 + 2x_2 + S_1^2 - 2) -$$

$$u_1(-x_1 + S_2^2) - u_2(-x_2 + S_3^2)$$

(e) Now, ^{firstly,} find the partial derivatives. The necessary & sufficient conditions are (3)

$$\frac{\partial L}{\partial x_1} = 4 - 2x_2 - d_1 + u_1 - 4x_1 = 0$$

$$\frac{\partial L}{\partial x_2} = 6 - 2x_1 - 2d_1 + u_2 - 4x_2 = 0$$

$$\frac{\partial L}{\partial d_1} = -x_1 - 2x_2 - s_1^2 + 2 = 0$$

$$\frac{\partial L}{\partial u_1} = u_1 x_1 = 0$$

$$\& \frac{\partial L}{\partial u_2} = u_2 x_2 = 0$$

$$\frac{\partial L}{\partial s_1} = d_1 s_1^2 = 0$$

Assume, ~~s~~ $s_1^2 = s_1$.

The complementary slackness conditions ($u_1 x_1 = 0, u_2 x_2 = 0$ & $d_1 s_1 = 0$) are helpful to find the leaving & entering vector.

Step 2:- Construct the modified L.P.P.

Introducing the artificial variables A_1 & A_2 the modified L.P.P becomes

$$\text{Max } Z = -A_1 - A_2$$

$$4x_1 + 2x_2 + d_1 - u_1 + A_1 = 4 \quad \left\{ \text{it is from } \frac{\partial L}{\partial x_1} = 0 \right\}$$

$$2x_1 + 2d_1 - u_2 + 4x_2 + A_2 = 6 \quad \left\{ \text{from } \frac{\partial L}{\partial x_2} = 0 \right\}$$

$$x_1 + 2x_2 + s_1 = 2 \quad \left\{ \begin{array}{l} \text{Here, we don't} \\ \text{need any artificial} \\ \text{variable b/c we} \\ \text{have identity (as } s_1 \end{array} \right\}$$

& Complementary slackness conditions are.

$$u_1 x_1 = 0, u_2 x_2 = 0 \& d_1 s_1 = 0$$

Matrix representation of the above problem is

$$\begin{bmatrix}
 x_1 & x_2 & d_1 & u_1 & u_2 & A_1 & A_2 & S_1 \\
 4 & 2 & 1 & -1 & 0 & 1 & 0 & 0 \\
 2 & 4 & 2 & 0 & -1 & 0 & 1 & 0 \\
 1 & 2 & 0 & 0 & 0 & 0 & 0 & 1
 \end{bmatrix}
 \begin{bmatrix}
 x_1 \\
 x_2 \\
 d_1 \\
 u_1 \\
 u_2 \\
 A_1 \\
 A_2 \\
 S_1
 \end{bmatrix}
 =
 \begin{bmatrix}
 4 \\
 6 \\
 2
 \end{bmatrix}$$

Step 3: Construct initial table of Phase-I.

Basic Var	CB	Cj	0	0	0	0	0	-1	-1	0	Min Ratio
		KB	x1	x2	d1	u1	u2	A1	A2	S1	
A1	-1	4	4	2	1	-1	0	1	0	0	1 →
A2	-1	6	2	4	2	0	-1	0	1	0	3
S1	0	2	1	2	0	0	0	0	0	1	2
Z = CB KB = -10		Δj	-6 ↑	-6	-3	1	1	0	0	0	

Remark: With the exceptional condition of complementary slackness, we need to modify the slackness conditions. Thus while to introduce S1 we must first ensure that

- (1) either d1 is the solⁿ (in basic variable column)
 - (2) d1 will be remove when S1 enter (in basic variable column)
- * Artificial variable should be removed first from basic variable column

Basic Variable	C _B	C _j X _B	0 0 0 0 0 -1 -1 0							Min Ratio	
			X ₁	X ₂	d ₁	u ₁	u ₂	A ₁	A ₂		S ₁
X ₁	0	1	1	1/2	1/4	-1/4	0	1/4	0	0	2
A ₂	-1	4	0	3	3/2	-1/2	-1	-1/2	1	0	4/3
S ₁	0	1	0	3/2	-1/4	1/4	0	-1/4	0	1	2/3 →
Z = -4	-	A _j	0	-3↑	-3/2	-1/2	-1	3/2	0	0	

Remark

Here d₁ cannot be entering vector in basic solⁿ since S₁ is in basic solⁿ.

Similarly for u₁. due to the slackness condition.

Basic Variable	C _B	C _j X _B	0 0 0 0 0 -1 -1 0							Min Ratio	
			X ₁	X ₂	d ₁	u ₁	u ₂	A ₁	A ₂		S ₁
X ₁	0	2/3	1	0	1/3	-1/3	0	1/3	0	-1/3	2
A ₂	-1	2	0	0	2	0	-1	0	1	-2	1 →
X ₂	0	2/3	0	1	-1/6	1/6	0	-1/6	0	2/3	-
Z = -2	-	A _j	0	0	-2↑	0	1	1	1	2	

{ Here d₁ can enter in basic variable column }

Basic Variable	C _B	C _j X _B	0 0 0 0 0 -1 -1 0							Min Ratio	
			X ₁	X ₂	d ₁	u ₁	u ₂	A ₁	A ₂		S ₁
X ₁	0	1/3	1	0	0	-1/3	1/6	1/3	-1/6	0	
d ₁	0	1	0	0	1	0	-1/2	0	1/2	-1	
X ₂	0	5/6	0	1	0	1/6	-1/2	-1/6	1/2	1/2	
Z = 0	-	A _j	0	0	0	0	0	1	1	0	

Since both A₁ & A₂ are out of the basic solⁿ.

The optimum solⁿ is X₁ = 1/3, X₂ = 5/6, Max Z = 5/6.

Q2:- Apply Wolfe's method to solve it.

$$\text{Max } Z = 2x_1 + x_2 - x_1^2$$

$$\text{s.t. } 2x_1 + 3x_2 \leq 6$$

$$2x_1 + x_2 \leq 4$$

$$\& x_1, x_2 \geq 0$$

$$x_1 = \frac{2}{3}, x_2 = \frac{14}{9}, Z = \frac{22}{9}$$

Ans

$$\text{Max } Z = 2x_1 + x_2 - x_1^2$$

$$2x_1 + 3x_2 + s_1^2 = 6$$

$$2x_1 + x_2 + s_2^2 = 4$$

$$-x_1 + \mu_1^2 = 0$$

$$-x_2 + \mu_2^2 = 0$$

$$L(x, s, \mu, d, \mu) = (2x_1 + x_2 - x_1^2) - d_1(2x_1 + 3x_2 + s_1^2 - 6) -$$

$$d_2(2x_1 + x_2 + s_2^2 - 4) - \mu_1(-x_1 + \mu_1^2) - \mu_2(-x_2 + \mu_2^2)$$

$$\frac{\partial L}{\partial x_1} = 2 - 2x_1 - 2d_1 - 2d_2 + \mu_1 = 0$$

$$\frac{\partial L}{\partial x_2} = 1 - 3d_1 - d_2 + \mu_2 = 0$$

$$\frac{\partial L}{\partial d_1} = -(2x_1 + 3x_2 + s_1^2 - 6) = 0$$

$$\frac{\partial L}{\partial d_2} = 2x_1 + x_2 + s_2^2 - 4 = 0$$

$$-2d_1 - s_1 = 0$$

$$-2d_1 - 2d_2 = 0$$

$$-2u_1 - u_2 = 0, -2u_1 - u_2 = 0$$

slackness variable

The construct modified linear programming problem.

$$2x_1 + 2d_1 + 2d_2 - u_1 + A_1 = 2$$

$$3d_1 + d_2 - u_2 + A_2 = 1$$

$$2x_1 + 3x_2 + s_1 = 6$$

$$2x_1 + x_2 + s_2 = 4$$

B.V.	CB	x_B	x_1	x_2	d_1	d_2	u_1	u_2	A_1	A_2	s_1	s_2	Min Ratio
A_1	+	2	<u>2</u>	0	2	2	-1	0	1	0	0	0	1 →
A_2	+	1	0	0	3	1	0	+	0	1	0	0	
s_1	0	6	2	3	0	0	0	0	0	0	1	0	3
s_2	0	4	2	1	0	0	0	0	0	0	0	1	2
$Z = -3$		Δ_j	2↑	0	5	3	-1	-1	0	0	0	0	
x_1	0	1	1	0	1	1	-1/2	0	1/2	0	0	0	-
A_2	+	1	0	0	3	1	0	-1	0	1	0	0	∴ 3
s_1	0	4	0	<u>3</u>	-2	-2	1	0	-1	0	1	0	1.33 →
s_2	0	2	0	1	-2	-2	1	0	-1	0	0	1	2
$Z = -1$		Δ_j	0	0↑	3	1	0	-1	-1	0	0	0	
x_1	0	1	1	0	1	1	-1/2	0	1/2	0	0	0	1
A_2	+	1	0	0	<u>3</u>	1	0	-1	0	1	0	0	1/3 →
x_2	0	4/3	0	1	-2/3	-2/3	1/3	0	-1/3	0	1/3	0	-
s_2	0	2/3	0	0	-4/3	-4/3	2/3	0	-2/3	0	-1/3	1	-
$Z = -1$		Δ_j	0	0	3	1	0	-1	-1	0	0	0	
x_1	0	2/3	1	0	0	2/3	-1/2	1/3	1/2	-1/3	0	0	
A_1	0	1/3	0	0	1	1/3	0	-1/3	0	1/3	0	0	
x_2	0	14/9	0	1	0	-4/9	1/3	-2/9	-1/3	2/9	1/3	0	
s_2	0	10/9	0	0	0	-8/9	-2/9	-4/9	-2/3	4/9	-1/3	1	
$Z = 0$		Δ_j	0	0	0	0	0	0	0	0	1	1	0

Hence The optimum soln is

$$\left. \begin{array}{l} x_1 = 213 \\ x_2 = 1419 \\ z = 2249 \end{array} \right\} \underline{z = 2249} \quad \underline{\text{Ans}}$$

Solu:- Max $Z = 2x_1 + 3x_2 - x_1^2$

$$x_1 + 2x_2 + s_1 = 4$$

$$-x_1 + u_1 = 0$$

$$-x_2 + u_2 = 0$$

The Lagrange's function is

$$L(x_1, x_2, s_1, u_1, u_2, d_1, u_1, u_2) = (2x_1 + 3x_2 - x_1^2) - d_1(x_1 + 2x_2 + s_1 - 4)$$

$$- u_1(-x_1 + u_1) - u_2(-x_2 + u_2)$$

Kuhn-Tucker conditions as follows-

$$\frac{\partial L}{\partial x_1} = 2 - 2x_1 - d_1 + u_1 = 0$$

$$\frac{\partial L}{\partial x_2} = 3 - 2d_1 + u_2 = 0$$

$$\frac{\partial L}{\partial d_1} = x_1 + 2x_2 + s_1 = 4$$

$$x_1 = 0$$

$$x_2 = 2$$

So construct the modified L.P.P. -

$$\text{Max } Z = 2x_1 + 3x_2 - x_1^2$$

$$x_1 + 2x_2 + s_1 = 4 \quad 2x_1 + d_1 - u_1 = 2$$

$$2d_1 - u_2 = 3$$

$$x_1 + 2x_2 + s_1 = 4$$

So construct initial table of phase I.

B.V.	CB	C_j X_B	0	0	0	0	0	-1	-1	0	Min Ratio
			x_1	x_2	d_1	u_1	u_2	A_1	A_2	S_1	
A_1	-1	2	2	0	1	-1	0	1	0	0	1 →
A_2	-1	3	0	0	2	0	-1	0	1	0	-
S_1	0	4	1	2	0	0	0	0	0	1	4
$Z = 0$	Δ_j		2	0	1	-1	-1	0	0	0	
x_1	0	1	1	0	1/2	-1/2	0	1/2	0	0	
A_2	-1	3	0	0	2	0	-1	0	1	0	
S_1	0	3	0	2	-1/2	1/2	0	-1/2	0	1	
$Z = -3$	Δ_j		0	0	2	0	-1	-1	0	0	

CBV	CB	C_j KB	0	0	0	0	0	-1	-1	0	Min Ratio
			x_1	x_2	d_1	u_1	u_2	A_1	A_2	S_1	
x_1	0	1	1	0	1/2	-1/2	0	1/2	0	0	2
A_2	-1	3	0	0	2	0	-1	0	1	0	3/2 →
x_2	0	3/2	0	1	-1/4	1/4	0	-1/4	0	1/2	-
$Z = -3$		Δ_j	0	0	2 ↑	0	-1	-1	0	0	
x_1	0	1/4	1	0	0	-1/2	1/4	1/2	-1/4	0	
d_1	0	3/2	0	0	1	0	-1/2	0	1/2	0	
x_2	0	15/8	0	1	0	1/4	-1/8	-1/4	1/8	1/2	
$Z = 0$		Δ_j	0	0	0	0	0	0	0	0	

Since all $\Delta_j \leq 0$. Hence the optimal solⁿ is

$$x_1 = 1/4, x_2 = \frac{15}{8}, \text{Max } Z = \frac{97}{16} \text{ Ans}$$

Method-2

Beale's Method

Beale's Method :- Another approach to solve Q.P.P. has been suggested by Beale's.

This method involves partitioning of variables into basic or non-basic variable. At each iteration the objective function is expressed

in terms of non-basic variable only. Let the

O.P.P be of the form.

$$\text{Max } f(x) = cx + \frac{1}{2} x^T Q x$$

$$\text{s. to } Ax = b$$

$$x \geq 0$$

where $x = [x_1, x_2, \dots, x_{m+n}]'$, $c = 1 \times m$

and A is $m \times (n+m)$ and Q is symmetric matrix.

The Beale's iteration procedure can be outline in following steps.

Step 1: First express the given O.P.P with linear constraint in the following form by introducing slack & surplus variable.

Step 2: Select arbitrary m variables as basic & remaining n as non basic. With this partitioning, constraint eqn $Ax = b$ can be written as:

$$(B, R) \begin{bmatrix} x_B \\ x_{NB} \end{bmatrix} = b \quad \text{--- (i)}$$

$$\text{or } Bx_B + Rx_{NB} = b$$

where x_B - denote basic variable

x_{NB} - denotes the non basic variable.

Also matrix A is partitioned of sub matrix B & R corresponding to x_B & x_{NB} respectively. According to partitioning eqn (i) can be written as

$$x_B = B^{-1} (b - Rx_{NB})$$

Express the basic variable x_B in terms of non basic ^{variable} x_{NB} using the given an additional constraint eqn.

Step 3: Express the objective funcⁿ $f(x)$ in terms of x_B & x_{NB} . Thus we observed that by increasing value of any non-basic variable the value of objective funcⁿ can be improved. It is important to note that the constraint in new problem become

$$B^{-1} R x_{NB} = B^{-1} b$$

Thus any component of x_{NB} can increase only until $\frac{\partial f}{\partial x_{NB}}$ becomes zero or one or more components of x_B are reduced to zero.

Step 4: We now have possibility of having more than m non-zero variable at any step of iteration. This stage comes when the new point is generated at some steps occurs, where $\frac{\partial f}{\partial x_{NB}}$ becomes zero.

Geometrically it means that we no longer have a basic solⁿ with respect to the original constraint set. When this happens we define a new variable $s_i = \frac{\partial f}{\partial x_{NB}}$ & the new constraint $s_i = 0$

Step 5: We now have $m+1$ non-basic variable & $m+1$ constraint which is a basic solⁿ to the extended set of constraints. We repeat the outline procedure until no further improvement in the objective funcⁿ may be obtained by increasing one of the non-basic variable.

Beale's Method:

(1)

$$\text{Q} \rightarrow \text{Min } z = -4x_1 + x_1^2 - 2x_1x_2 + 2x_2^2$$

$$\text{Subject to, } \begin{aligned} 2x_1 + x_2 &\geq 6 \\ x_1 - 4x_2 &\geq 0 \\ \& \ x_1, x_2 \geq 0 \end{aligned}$$

Solⁿ:

Step 1: Convert the minimization problem into maximization & adding surplus variables s_1 and s_2

$$\text{Max } z = 4x_1 - x_1^2 + 2x_1x_2 - 2x_2^2$$

$$2x_1 + x_2 - s_1 = 6$$

$$x_1 - 4x_2 - s_2 = 0$$

Step 2: Selecting arbitrary m variables as basic variables & so that remaining $n-m$ variables become non-basic variables

Here, Making s_1 & s_2 basic variable in the initial solⁿ

and expressing these in terms of non-basic variables x_1 & x_2

$$\text{Here } x_B = s_1 \& s_2 \quad \& \quad x_{NB} = x_1 \& x_2$$

$$s_1 = -6 + 2x_1 + x_2$$

$$s_2 = x_1 - 4x_2$$

$$f(x) = z = 4x_1 - x_1^2 + 2x_1x_2 - 2x_2^2$$

Step 3:

Examine the partial derivative of $f(x)$ formulate with respect to non-basic variable & put the non-basic variable equal to zero

$$\left. \frac{\partial z}{\partial x_1} \right|_{\substack{x_1=0 \\ x_2=0 \\ x_1 \geq 0}} = 4 - 2x_1 - 2x_2 \Big|_{\substack{x_1=0 \\ x_2=0}} = 4$$

$$\left. \frac{\partial z}{\partial x_2} \right|_{\substack{x_1=0 \\ x_2=0}} = -2x_1 + 2x_1 - 4x_2 \Big|_{\substack{x_1=0 \\ x_2=0}} = 0$$

Step 4:- If $\left[\frac{\partial f(x)}{\partial x_{NB}} \right]_{x_{NB}=0} > 0$ for at least one.

Choose the most positive one & the corresponding non-basic variable will enter in the basis

Here $\left. \frac{\partial z}{\partial x_1} \right|_{\substack{x_1=0 \\ x_2=0}} = 4 > 0$

Clearly x_1 will enter in the basis. Compute the minimum ratio. $\min \left\{ \frac{b_i}{\text{coeff of } x_1 \text{ in the constraint}}, \frac{b_i}{\text{coeff of } x_1 \text{ in the corr constraint}} \right\}$

$\min \left\{ \frac{-6}{1 \times 1}, \frac{0}{\text{coeff}(x_1)} \right\}$

If the minimum ratio occurs $\frac{b_i}{a_{ik}}$ the corresponding basic variable leave the basis. i.e. the variable s_i is eligible to leave the basis.

Step 5:-

Now Expressing the new basic variable x_1, s_2 in terms of new non basic variables x_2 & s_1

$x_1 = 3 - \frac{1}{2}x_2 + \frac{1}{2}s_1$

$s_2 = 3 - \frac{1}{2}x_2 + \frac{1}{2}s_1 - 4x_2$

$= 3 - \frac{9}{2}x_2 + \frac{1}{2}s_1$

$\left. \begin{matrix} \text{but the value of } x_1 \\ \text{because it is basic} \\ \text{variable now} \end{matrix} \right\}$

$z = 4x_1 - x_1^2 + 2x_1x_2 - 2x_2^2$ $\left. \begin{matrix} \text{but the value of } x_1 \text{ in } z \end{matrix} \right\}$

$z = 4 \left(3 - \frac{1}{2}x_2 + \frac{1}{2}s_1 \right) - \left(3 - \frac{1}{2}x_2 + \frac{1}{2}s_1 \right)^2 + 2 \left(3 - \frac{1}{2}x_2 + \frac{1}{2}s_1 \right) x_2 - 2x_2^2$

$z = 9 + x_2 - s_1 + \frac{3}{2}x_2s_1 - \frac{13}{4}x_2^2 - \frac{1}{4}s_1^2$

Here $x_B = (x_1, s_2)$ & $x_{NB} = (x_2, s_1)$.

Sub 6

Again Diff Z with respect to non-basic variable
& put the non-basic variables equal to zero,

$$\left. \frac{\partial Z}{\partial x_2} \right|_{\substack{x_2=0 \\ s_2=0}} = 1 + \frac{3}{2}s_1 - \frac{13}{2}x_2 \Big|_{\substack{x_2=0 \\ s_2=0}} = 1$$

$$\left. \frac{\partial Z}{\partial s_1} \right|_{\substack{x_2=0 \\ s_1=0}} = -1 + \frac{3}{2}x_2 - \frac{1}{4}s_1 \Big|_{\substack{x_2=0 \\ s_1=0}} = -1$$

Choose the most positive one & the corresponding non-basic variable will enter in the basis

Here $\frac{\partial Z}{\partial x_2} = 1 > 0$

clearly x_2 will enter in the basis. Now, compute the minimum ratio

$$\min \left\{ \frac{+3}{-1/2}, \frac{9}{-9/2} \right\} = \min \{ \alpha, \beta/9 \} = 6/9$$

$\{ \alpha, \beta \}$

If the minimum ratio γ the exit criterion corresponding to a non-basic variable. In this case introduce ~~artificial~~ additional non-basic variable called a free variable

defined by $u = 1/2 \frac{\partial Z}{\partial x_2}$

Step 7

Since the minimum ratio is corresponding to β .

We introduce a non-basic free variable u , defined by

$$u = 1/2 \frac{\partial Z}{\partial x_2} = 1/2 + 3/4 s_1 - 13/4 x_2$$

Expressing basic variable & Z in terms of x_{NB}

$$x_B = (x_1, x_2, s_2) \quad x_{NB} = (s_1, u)$$

$$x_2 = \frac{2}{13} + \frac{3}{13} s_1 - \frac{4}{13} u_1 \quad \text{--- (A)}$$

$$x_1 = \frac{30}{13} - \frac{3}{26} s_1 + \frac{2}{13} u_1 \quad \text{--- (B)}$$

$$s_2 = \frac{30}{13} - \frac{27}{26} s_1 + \frac{10}{13} u_1 \quad \text{--- (C)}$$

$$f \quad z = 9 + \frac{1}{13} [2 + 3s_2 - 4u_1] - s_2 - \frac{3}{26} [2 + 3s_1 - 4u_1] - s_1 \\ - \frac{1}{52} (2 + 3s_2 - 4u_1)^2 - \frac{1}{4} s_1^2$$

Again

$$\left. \frac{\partial z}{\partial s_1} \right|_{\substack{s_1=0 \\ u_1=0}} = -9/13$$

$$\left. \frac{\partial z}{\partial u_1} \right|_{\substack{s_1=0 \\ u_1=0}} = 0$$

Here $\frac{\partial z}{\partial s_1} < 0$ & $\frac{\partial z}{\partial u_1} = 0$

So the optimum value of z is obtained by setting $u_1 = 0$ & $s_1 = 0$ in the current value of objective funcⁿ

$$z^* = 9 + \frac{2}{13} - \frac{2}{52} = \frac{474}{52}$$

Hence the optimal solⁿ of given problem is put the non-basic variable equal zero in (A), (B) & (C)

$$\left. \begin{aligned} x_1 &= 30/13, \quad x_2 = 2/13 \\ \& \quad z_{\min} &= 9.115 \end{aligned} \right\} \underline{\text{Ans}}$$

$$z = 100,$$

$$\text{Q2: } \text{Max } z = 10x_1 + 25x_2 - 10x_1^2 - x_2^2 - 4x_1x_2$$

$$x_1 + 2x_2 + x_3 = 10$$

$$x_1 + x_2 + x_4 = 9$$

$$x_1, x_2, x_3, x_4 \geq 0$$

Same as last question.

Selecting x_1 & x_2 arbitrarily to be the basic variables
we obtain $x_1 = 8 + x_3 - 2x_4$, $x_2 = 1 - x_3 + x_4$ where

$$x_B = (x_1, x_2), \quad x_{NB} = (x_3, x_4)$$

Step 2: Now expressing z in terms of (x_3, x_4) gives.

$$f(x_3, x_4) = 10(8 + x_3 - 2x_4) + 25(1 - x_3 + x_4) + 10(8 + x_3 - 2x_4)^2 - (1 - x_3 + x_4)^2 - 4(8 + x_3 - 2x_4)(1 - x_3 + x_4)$$

$$\frac{\partial f(x_{NB})}{\partial x_3} = 10 - 25 - 20(8 + x_3 - 2x_4) + 2(1 - x_3 + x_4) - 4(1 - x_3 + x_4) + 4(8 + x_3 - 2x_4)$$

$$\left(\frac{\partial f}{\partial x_3} \right)_{x_3=x_4=0} = -145$$

This indicates that objective func will decrease if x_3 is increased. This happens contrary to our desire to increase the objective function. The partial derivative with respect to x_4 will give us a more suitable alternative.

$$\left(\frac{\partial f}{\partial x_4} \right) = -20 + 25 + 40(8 + x_3 - 2x_4) - 2(1 - x_3 + x_4) + 8(1 - x_3 + x_4) - 4(8 + x_3 - 2x_4)$$

$$\left(\frac{\partial f}{\partial x_4} \right)_{x_3=x_4=0} = 299$$

Step 3: If x_4 is increased to a value greater than 4, x_1 will become negative since $x_1 = 8 + x_3 - 2x_4$ & $x_3 = 0$ The partial derivatives become zero at $x_4 = \frac{299}{66}$

Taking minimum of $(4, \frac{299}{66})$, we find $x_4 = 4$, and new basic variables are x_4 & x_2 . We now start with new iteration.

Second iteration:- Step 4:- We start with solving for x_2 & x_4 in terms of x_1 & x_3 . Thus.

$$x_2 = 5 - \frac{1}{2}(x_1 + x_3), \quad x_4 = 4 + \frac{1}{2}(x_3 - x_1)$$

$$x_B = (x_2, x_4), \quad x_{NB} = (x_1, x_3)$$

Expressing z in terms of (x_1, x_3) gives.

$$f(x_1, x_3) = 10x_1 + 25[5 - \frac{1}{2}(x_1 + x_3)] - 10x_1^2 - [5 - \frac{1}{2}(x_1 + x_3)]^2 - 4x_1[5 - \frac{1}{2}(x_1 + x_3)]$$

$$\left(\frac{\partial f}{\partial x_1}\right)_{x_1=x_2=0} = -\frac{15}{2}$$

Since both the partial derivatives are -ive, hence neither x_1 nor x_3 non-basic variables can be introduced to increase z and thus the optimal soln has been obtained.

The optimal soln is given by.

$$x_1 = x_3 = 0, \quad x_2 = 5, \quad x_4 = 4 \quad \underline{\underline{\text{Ans}}}$$

Q6 Max $z = 2x_1 + x_2 - x_1^2$

$$2x_1 + 3x_2 \leq 6$$

$$2x_1 + x_2 \leq 4$$

$$x_1, x_2 \geq 0$$

$$2x_1 + 3x_2 + x_3 = 6$$

$$2x_1 + x_2 + x_4 = 4$$

Selecting x_1 & x_2 arbitrarily to the basic variables

we obtain
$$x_1 = \frac{1}{2}(2 + x_3 + x_4)$$

$$2x_2 + x_3 - x_4 = 2$$

$$\& \quad x_2 = \frac{1}{2}(2 + x_3 + x_4)$$

$$-4x_1 + x_3 - 3x_4 = -6$$

$$x_1 = \frac{1}{4}(6 + 3x_4 - x_3)$$

Putting the value of x_1 & x_2 in eqn (i), the func
 $f = \frac{1}{2} (6 + x_3 - 2x_4) + \frac{1}{2} (2 - x_3 + x_4) - \left(\frac{3}{2} + \frac{1}{4}x_3 - \frac{3}{4}x_4\right)^2$

$$\frac{\partial f}{\partial x_3} = \frac{1}{2} - \frac{1}{2} \cdot 2 \left(\frac{3}{2} + \frac{1}{4}x_3 - \frac{3}{4}x_4\right) \cdot \frac{1}{4}$$

$$= -\frac{3}{4} - \frac{1}{8}x_3 + \frac{3}{8}x_4$$

$$\frac{\partial f}{\partial x_4} = \frac{5}{4} + \frac{3}{8}x_3 - \frac{9}{8}x_4$$

$$\left. \frac{\partial f}{\partial x_3} \right|_{x_3=x_4=0} = -3/4$$

$$\left. \frac{\partial f}{\partial x_4} \right|_{x_3=x_4=0} = 5/4$$

Since x_3 is negative (x_4) gives better improvement to objective func by increased the value of x_4 , now,

Since x_1 gives negative value when x_4 increase to greater than 2, and

$$\left. \frac{\partial f}{\partial x_4} \right| = 0 \Rightarrow \frac{5}{4} - \frac{9}{8}x_4 \Rightarrow x_4 = 10/9$$

$$\min(x_4) = \min(2, 10/9) = 10/9 \text{ Ans}$$

Iteration-2:- Now, let $x_B = (x_2, x_4)$ & $x_{NB} = (x_1, x_3)$

$$x_2 = \frac{1}{3} (6 - x_3 - 2x_1), \quad x_4 = 4 - 2x_1 - x_2$$

put the value of x_2 & x_4 in eqn (i)

$$f = 2x_1 + \frac{1}{3} (6 - x_3 - 2x_1) - x_1^2$$

$$\frac{\partial f}{\partial x_1} = 2 - \frac{2}{3} - 2x_1 = \frac{4}{3} - 2x_1$$

$$\left. \frac{\partial f}{\partial x_1} \right|_{x_2=x_3=0} = 4/3$$

$$\frac{\partial f}{\partial x_3} = -1/3 \text{ [Which is -ive]}$$

Since x_1 is gives better improvement to objective func by increased the value of x_1 , now,

$$\left. \frac{\partial f}{\partial x_1} \right|_{x_3=0} = 0 = \frac{4}{3} - 2x_1 \geq 0 \Rightarrow x_1 = \frac{2}{3}$$

$$\min(x_1) = \min(3, \frac{2}{3}) = \frac{2}{3}$$

Iteration III:- Now let $x_B = (x_1, x_4)$ & $x_{NB} = (x_2, x_3)$

$$x_4 = \frac{1}{2}(6 - 3x_2 - x_3), \quad x_1 = 4 - 2x_2 - x_3$$

$$f = (6 - 3x_2 - x_3) + x_2 - \frac{1}{4}(6 - 3x_2 - x_3)^2$$

$$\frac{\partial f}{\partial x_2} = 7 - \frac{9}{2}x_2 + \frac{3}{2}x_3 \quad \left. \frac{\partial f}{\partial x_2} \right|_{x_2=x_3=0} = 7$$

$$\left. \frac{\partial f}{\partial x_3} \right| = 2 - \frac{3}{2}x_3 - \frac{1}{2}x_3 \quad \left. \frac{\partial f}{\partial x_3} \right|_{x_2=x_3=0} = 2$$

$$\left. \frac{\partial f}{\partial x_2} \right|_{x_3=0} = 7 - \frac{9}{2}x_2 = 0 \Rightarrow x_2 = \frac{14}{9}$$

$$\min(x_2) = \frac{14}{9}$$

Hence the optimal solution at $x_1 = \frac{2}{3}, x_2 = \frac{14}{9}, z = \frac{22}{9}$ Ans