

RIC603 CONTROL SYSTEM-I

Unit	Topic	Lectures
I	Basic Components of a control system, Feedback and its effect, types of feedback control systems. Block diagrams Reduction and signal flow graphs, Modeling of Physical systems: electrical networks, mechanical systems elements, equations of mechanical systems, sensors and encoders in control systems, DC motors in control systems, Analogous Systems.	8
II	State-Variable Analysis: Vector matrix representation of state equation, state transition matrix, state-transition equation, relationship between state equations and high-order differential equations, relationship between state equations and transfer functions. Similarity Transformation, Decomposition of transfer functions, Controllability and observability, Eigen Value and Eigen Vector, Diagonalization.	8
III	Time domain Analysis of Control Systems: Time response of continuous data systems, typical test signals for the time response of control systems, the unit step response and time-domain specifications, Steady-State error, time response of a first order system, transient response of a prototype second order system.	8
IV	Stability of Linear Control Systems: Bounded-input bounded-output stability continuous data systems, zero-input and asymptotic stability of continuous data systems, Routh Hurwitz criterion. Root-Locus Technique: Introduction, Properties of the Root Loci, Design aspects of the Root Loci.	8
V	Frequency Domain Analysis: M_r (resonant peak) and ω_r (resonant frequency) and bandwidth of the prototype Second order system, effects of adding a zero to the forward path, effects of adding a pole to the forward path, Polar Plot, Nyquist stability criterion, relative stability: gain margin and phase margin, stability analysis with the Bode plot.	8